

Line graphs and geodesic transitivity*

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Abstract

For a graph Γ , a positive integer s and a subgroup $G \leq \text{Aut}(\Gamma)$, we prove that G is transitive on the set of s -arcs of Γ if and only if Γ has girth at least $2(s - 1)$ and G is transitive on the set of $(s - 1)$ -geodesics of its line graph. As applications, we first classify 2-geodesic transitive graphs of valency 4 and girth 3, and determine which of them are geodesic transitive. Secondly we prove that the only non-complete locally cyclic 2-geodesic transitive graphs are the octahedron and the icosahedron.

Keywords: Line graphs, s -geodesic transitive graphs, s -arc transitive graphs.

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1 Introduction

A geodesic from a vertex u to a vertex v in a graph is a path of shortest length from u to v . In the infinite setting geodesics play an important role, for example, in the classification of infinite distance transitive graphs [11], and in studying locally finite graphs, see for example, [17]. They are also used to model, in a finite network, the notion of visibility in Euclidean space [22]. Here we study transitivity properties on geodesics in finite graphs. Throughout this paper, we assume that all graphs are finite simple and undirected.

Let Γ be a connected graph with vertex set $V(\Gamma)$, edge set $E(\Gamma)$ and automorphism group $\text{Aut}(\Gamma)$. For a positive integer s , an s -arc of Γ is an $(s + 1)$ -tuple (v_0, v_1, \dots, v_s) of vertices such that v_i, v_{i+1} are adjacent and $v_{j-1} \neq v_{j+1}$ for $0 \leq i \leq s - 1$, $1 \leq j \leq s - 1$; it is an s -geodesic if in addition v_0, v_s are at distance s . For $G \leq \text{Aut}(\Gamma)$, Γ is said to be (G, s) -arc transitive or (G, s) -geodesic transitive, if Γ contains an s -arc or s -geodesic,

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and G is transitive on the set of t -arcs or t -geodesics respectively for all $t \leq s$. Moreover, if $G = \text{Aut}(\Gamma)$, then G is usually omitted in the previous notation. The study of (G, s) -arc transitive graphs goes back to Tutte's papers [18, 19] which showed that if Γ is a (G, s) -arc transitive cubic graph then $s \leq 5$. About twenty years later, relying on the classification of finite simple groups, Weiss [21] proved that there are no $(G, 8)$ -arc transitive graphs with valency at least three. The family of s -arc transitive graphs has been studied extensively, see [2, 9, 15, 16, 20]. Here we consider these properties for line graphs.

The *line graph* $L(\Gamma)$ of a graph Γ is the graph whose vertices are the edges of Γ , with two edges adjacent in $L(\Gamma)$ if they have a vertex in common. Our first aim in the paper is to investigate connections between the s -arc transitivity of a connected graph Γ and the $(s - 1)$ -geodesic transitivity of its line graph $L(\Gamma)$ where $s \geq 2$. A key ingredient in this study is a collection of injective maps \mathcal{L}_s , where \mathcal{L}_s maps the s -arcs of Γ to certain s -tuples of edges of Γ (vertices of $L(\Gamma)$) as defined in Definition 2.3. The major properties of \mathcal{L}_s are derived in Theorem 2.4 and the main consequence linking the symmetry of Γ and $L(\Gamma)$ is given in Theorem 1.1, which is proved in Subsection 2.2.

We denote by $\Gamma(u)$ the set of vertices adjacent to the vertex u in Γ . If $|\Gamma(u)|$ is independent of $u \in V(\Gamma)$, then Γ is said to be *regular*. The *girth* of Γ is the length of the shortest cycle; the *diameter* $\text{diam}(\Gamma)$ of Γ is the maximum distance between two vertices.

Theorem 1.1. *Let Γ be a connected regular, non-complete graph of girth g and valency at least 3. Let $G \leq \text{Aut}(\Gamma)$ and let s be a positive integer such that $2 \leq s \leq \text{diam}(L(\Gamma)) + 1$. Then G is transitive on the set of s -arcs of Γ if and only if $s \leq g/2 + 1$ and G is transitive on the set of $(s - 1)$ -geodesics of $L(\Gamma)$.*

It follows from a deep theorem of Richard Weiss in [21] that if Γ is a connected s -arc transitive graph of valency at least 3, then $s \leq 7$. This observation yields the following corollary, and its proof can be found in Subsection 2.2.

Corollary 1.2. *Let Γ and g be as in Theorem 1.1. Let s be a positive integer such that $2 \leq s \leq \text{diam}(L(\Gamma)) + 1$. If $L(\Gamma)$ is $(s - 1)$ -geodesic transitive, then either $2 \leq s \leq 7$ or $s > \max\{7, g/2 + 1\}$.*

Note that in a graph, 1-arcs and 1-geodesics are the same, and are called *arcs*. For graphs of girth at least 4, each 2-arc is a 2-geodesic so the sets of 2-arc transitive graphs and 2-geodesic transitive graphs are the same. However, there are also 2-geodesic transitive graphs of girth 3. For such a graph Γ , the subgraph $[\Gamma(u)]$ induced on the set $\Gamma(u)$ is vertex transitive and contains edges. Moreover, if $[\Gamma(u)]$ is complete, then so is Γ . A vertex transitive, non-complete, non-empty graph must have at least 4 vertices and thus valency 4 is the first interesting case.

As an application of Theorem 1.1, we characterise connected non-complete 2-geodesic transitive graphs of girth 3 and valency 4. In this case, $[\Gamma(u)] \cong C_4$ or $2K_2$ for each $u \in V(\Gamma)$. If Γ is s -geodesic transitive with $s = \text{diam}(\Gamma)$, then Γ is called *geodesic transitive*. A graph Γ is said to be *distance transitive* if its automorphism group is transitive on the ordered pairs of vertices at any given distance.

Theorem 1.3. *Let Γ be a connected non-complete graph of girth 3 and valency 4. Then Γ is 2-geodesic transitive if and only if Γ is either $L(K_4) \cong \mathcal{O}$ or $L(\Sigma)$ for a connected 3-arc transitive cubic graph Σ .*

Moreover, Γ is geodesic transitive if and only if $\Gamma = L(\Sigma)$ for a cubic distance transitive graph Σ , namely $\Sigma = K_4, K_{3,3}$, the Petersen graph, the Heawood graph or Tutte's 8-cage.

Since there are infinitely many 3-arc transitive cubic graphs, there are therefore infinitely many 2-geodesic transitive graphs with girth 3 and valency 4. Theorem 1.3 is proved in Section 3, and it provides a useful method for constructing 2-geodesic transitive graphs of girth 3 and valency 4 which are not geodesic transitive, an example being the line graph of a triple cover of Tutte's 8-cage constructed in [14]. The line graphs mentioned in the second part of Theorem 1.3 are precisely the distance transitive graphs of valency 4 and girth 3 given, for example, in [4, Theorem 7.5.3 (i)].

A graph Γ is said to be *locally cyclic* if $[\Gamma(u)]$ is a cycle for every vertex u . In particular, the girth of a locally cyclic graph is 3. It was shown in [8, Theorem 1.1] that for 2-geodesic transitive graphs Γ of girth 3, the subgraph $[\Gamma(u)]$ is either a connected graph of diameter 2, or isomorphic to the disjoint union mK_r of m copies of a complete graph K_r with $m \geq 2, r \geq 2$. Thus one consequence of Theorem 1.3 is a classification of connected, locally cyclic, 2-geodesic transitive graphs in Corollary 1.4: for $[\Gamma(u)] \cong C_n$ has diameter 2 only for valencies $n = 4$ or 5, and the valency 5, girth 3, 2-geodesic transitive graphs were classified in [7]. Its proof can be found at the end of Section 3. We note that locally cyclic graphs are important for studying embeddings of graphs in surfaces, see for example [10, 12, 13].

Corollary 1.4. *Let Γ be a connected, non-complete, locally cyclic graph. Then Γ is 2-geodesic transitive if and only if Γ is the octahedron or the icosahedron.*

2 Line graphs

We begin by citing a well-known result about line graphs.

Lemma 2.1. [1, p.1455] *Let Γ be a connected graph. If Γ has at least 5 vertices, then $\text{Aut}(\Gamma) \cong \text{Aut}(L(\Gamma))$.*

The *subdivision graph* $S(\Gamma)$ of a graph Γ is the graph with vertex set $V(\Gamma) \cup E(\Gamma)$ and edge set $\{\{u, e\} | u \in V(\Gamma), e \in E(\Gamma), u \in e\}$. The link between the diameters of Γ and $S(\Gamma)$ was determined in [6, Remark 3.1 (b)]: $\text{diam}(S(\Gamma)) = 2 \text{diam}(\Gamma) + \delta$ for some $\delta \in \{0, 1, 2\}$. Here, based on this result, we will show the connection between the diameters of Γ and $L(\Gamma)$ in the following lemma.

Lemma 2.2. *Let Γ be a connected graph with $|V(\Gamma)| \geq 2$. Then it holds $\text{diam}(L(\Gamma)) = \text{diam}(\Gamma) + x$ for some $x \in \{-1, 0, 1\}$. Moreover, all three values occur, for example, if $\Gamma = K_{3+x}$, then $\text{diam}(L(\Gamma)) = \text{diam}(\Gamma) + x = 1 + x$ for each x .*

Proof. Let $d = \text{diam}(\Gamma)$, $d_l = \text{diam}(L(\Gamma))$ and $d_s = \text{diam}(S(\Gamma))$. Let $(x_0, x_2, \dots, x_{2d_l})$ be a d_l -geodesic of $L(\Gamma)$. Then by definition of $L(\Gamma)$, each edge intersection $x_{2i} \cap x_{2i+2}$ is a vertex v_{2i+1} of Γ and $(x_0, v_1, x_2, \dots, v_{2d_l-1}, x_{2d_l})$ is a $2d_l$ -path in $S(\Gamma)$. Suppose that $(x_0, v_1, x_2, \dots, v_{2d_l-1}, x_{2d_l})$ is not a $2d_l$ -geodesic of $S(\Gamma)$. Then there is an r -geodesic from x_0 to x_{2d_l} , say $(y_0, y_1, y_2, \dots, y_r)$ with $y_0 = x_0$ and $y_r = x_{2d_l}$, such that $r < 2d_l$. Since both x_0, x_{2d_l} are in $V(L(\Gamma))$, it follows that r is even, and hence $d_{L(\Gamma)}(x_0, x_{2d_l}) = \frac{r}{2} < d_l$ which contradicts the fact that $(x_0, x_2, \dots, x_{2d_l})$ is a d_l -geodesic of $L(\Gamma)$. Thus

$(x_0, v_1, x_2, \dots, v_{2d_l-1}, x_{2d_l})$ is a $2d_l$ -geodesic in $S(\Gamma)$. It follows from [6, Remark 3.1 (b)] that $d_l \leq d_s/2 \leq d + 1$.

Now take a d_s -geodesic $(x_0, x_1, \dots, x_{d_s})$ in $S(\Gamma)$. If $x_0 \in E(\Gamma)$, then $(x_0, x_2, x_4, \dots, x_{2\lfloor d_s/2 \rfloor})$ is a $\lfloor d_s/2 \rfloor$ -geodesic in $L(\Gamma)$, so $d_l \geq \lfloor d_s/2 \rfloor \geq d$. Similarly we see that $d_l \geq d$ if $x_{d_s} \in E(\Gamma)$. Finally if both $x_0, x_{d_s} \in V(\Gamma)$, then d_s is even and $d_\Gamma(x_0, x_{d_s}) = d_s/2$. Moreover $(x_1, x_3, \dots, x_{d_s-1})$ is a $(\frac{d_s-2}{2})$ -geodesic in $L(\Gamma)$. By [6, Remark 3.1 (b)], $d_s = 2d$, so $d_l \geq \frac{d_s-2}{2} = d - 1$. □

2.1 The map \mathcal{L}_s

Let Γ be a finite connected graph. For each integer $s \geq 2$, we define a map from the set of s -arcs of Γ to the set of s -tuples of $V(L(\Gamma))$.

Definition 2.3. Let $\mathbf{a} = (v_0, v_1, \dots, v_s)$ be an s -arc of Γ where $s \geq 2$, and for $0 \leq i < s$, let $e_i := \{v_i, v_{i+1}\} \in E(\Gamma)$. Define $\mathcal{L}_s(\mathbf{a}) := (e_0, e_1, \dots, e_{s-1})$.

The following theorem gives some important properties of \mathcal{L}_s .

Theorem 2.4. Let $s \geq 2$, let Γ be a connected graph containing at least one s -arc, and let \mathcal{L}_s be as in Definition 2.3. Then the following statements hold.

(1) \mathcal{L}_s is an injective map from the set of s -arcs of Γ to the set of $(s - 1)$ -arcs of $L(\Gamma)$. Further, \mathcal{L}_s is a bijection if and only if either $s = 2$, or $s \geq 3$ and $\Gamma \cong C_m$ or P_n for some $m \geq 3, n \geq s$.

(2) \mathcal{L}_s maps s -geodesics of Γ to $(s - 1)$ -geodesics of $L(\Gamma)$.

(3) If $s \leq \text{diam}(L(\Gamma)) + 1$, then the image $\text{Im}(\mathcal{L}_s)$ contains the set \mathcal{G}_{s-1} of all $(s - 1)$ -geodesics of $L(\Gamma)$. Moreover, $\text{Im}(\mathcal{L}_s) = \mathcal{G}_{s-1}$ if and only if $\text{girth}(\Gamma) \geq 2s - 2$.

(4) \mathcal{L}_s is $\text{Aut}(\Gamma)$ -equivariant, that is, $\mathcal{L}_s(\mathbf{a})^g = \mathcal{L}_s(\mathbf{a}^g)$ for all $g \in \text{Aut}(\Gamma)$ and all s -arcs \mathbf{a} of Γ .

Proof. (1) Let $\mathbf{a} = (v_0, v_1, \dots, v_s)$ be an s -arc of Γ and let $\mathcal{L}_s(\mathbf{a}) := (e_0, e_1, \dots, e_{s-1})$ with the e_i as in Definition 2.3. Then each of the e_i lies in $E(\Gamma) = V(L(\Gamma))$ and $e_k \neq e_{k+1}$ for $0 \leq k \leq s - 2$. Further, since $v_j \neq v_{j+1}, v_{j+2}$ for $1 \leq j \leq s - 2$, we have $e_{j-1} \neq e_{j+1}$. Thus $\mathcal{L}_s(\mathbf{a})$ is an $(s - 1)$ -arc of $L(\Gamma)$.

Let $\mathbf{b} = (u_0, u_1, \dots, u_s)$ and $\mathbf{c} = (w_0, w_1, \dots, w_s)$ be two s -arcs of Γ . Then $\mathcal{L}_s(\mathbf{b}) = (f_0, f_1, \dots, f_{s-1})$ and $\mathcal{L}_s(\mathbf{c}) = (g_0, g_1, \dots, g_{s-1})$ are two $(s - 1)$ -arcs of $L(\Gamma)$, where $f_i = \{u_i, u_{i+1}\}$ and $g_i = \{w_i, w_{i+1}\}$ for $0 \leq i < s$. Suppose that $\mathcal{L}_s(\mathbf{b}) = \mathcal{L}_s(\mathbf{c})$. Then $f_i = g_i$ for each $i \geq 0$, and hence $f_i \cap f_{i+1} = g_i \cap g_{i+1}$, that is, $u_{i+1} = w_{i+1}$ for each $0 \leq i \leq s - 2$. So also $u_0 = w_0$ and $u_s = w_s$, and hence $\mathbf{b} = \mathbf{c}$. Thus \mathcal{L}_s is injective.

Now we prove the second part. Each arc of $L(\Gamma)$ is of the form $\mathbf{h} = (e, f)$ where $e = \{u_0, u_1\}$ and $f = \{u_1, u_2\}$ are distinct edges of Γ . Thus $u_0 \neq u_2$, so $\mathbf{k} = (u_0, u_1, u_2)$ is a 2-arc of Γ and $\mathcal{L}_2(\mathbf{k}) = \mathbf{h}$. It follows that \mathcal{L}_2 is onto and hence is a bijection. If $s \geq 3$ and $\Gamma \cong C_m$ or P_n for some $m \geq 3, n \geq s$, then $L(\Gamma) \cong C_m$ or P_{n-1} respectively, and hence for every $(s - 1)$ -arc \mathbf{x} of $L(\Gamma)$, we can find an s -arc \mathbf{y} of Γ such that $\mathcal{L}_s(\mathbf{y}) = \mathbf{x}$, that is, \mathcal{L}_s is onto. Thus \mathcal{L}_s is a bijection. Conversely, suppose that \mathcal{L}_s is onto, and that $s \geq 3$. Assume that some vertex u of Γ has valency greater than 2 and let $e_1 = \{u, v_1\}, e_2 = \{u, v_2\}, e_3 = \{u, v_3\}$ be distinct edges. Then $\mathbf{x} = (e_1, e_2, e_3)$ is a 2-arc in $L(\Gamma)$ and there is no 3-arc \mathbf{y} of Γ such that $\mathcal{L}_s(\mathbf{y}) = \mathbf{x}$. In general, for $s = 3a + b \geq 4$ with $a \geq 1$ and $b \in \{0, 1, 2\}$, we concatenate a copies of \mathbf{x} to form an $(s - 1)$ -arc of $L(\Gamma)$: namely (\mathbf{x}^a) if $b = 0$; (\mathbf{x}^a, e_1) if $b = 1$; (\mathbf{x}^a, e_1, e_2) if $b = 2$. This $(s - 1)$ -arc does not lie in the image

of \mathcal{L}_s . Thus each vertex of Γ has valency at most 2. If all vertices have valency 2 then $\Gamma \cong C_m$ for some $m \geq 3$, since Γ is connected. So suppose that some vertex u of Γ has valency 1. Since Γ is connected and each other vertex has valency at most 2, it follows that $\Gamma \cong P_n$ for some $n \geq s$.

(2) Let $\mathbf{a} = (v_0, \dots, v_s)$ be an s -geodesic of Γ and let $\mathcal{L}_s(\mathbf{a}) = (e_0, \dots, e_{s-1})$ as above. If $s = 2$, then $\mathcal{L}_s(\mathbf{a})$ is a 1-arc, and hence a 1-geodesic of $L(\Gamma)$. Suppose that $s \geq 3$ and $\mathcal{L}_s(\mathbf{a})$ is not an $(s-1)$ -geodesic. Then $d_{L(\Gamma)}(e_0, e_{s-1}) = r < s-1$ and there exists an r -geodesic $\mathbf{r} = (f_0, f_1, \dots, f_{r-1}, f_r)$ with $f_0 = e_0$ and $f_r = e_{s-1}$. Since $s \geq 3$ and \mathbf{a} is an s -geodesic, it follows that $\{v_0, v_1\} \cap \{v_{s-1}, v_s\} = \emptyset$, that is, e_0 and e_{s-1} are not adjacent in $L(\Gamma)$. Thus $r \geq 2$. Since \mathbf{r} is an r -geodesic, it follows that the consecutive edges f_{i-1}, f_i, f_{i+1} do not share a common vertex for any $1 \leq i \leq r-1$, otherwise $(f_0, \dots, f_{i-1}, f_{i+1}, \dots, f_r)$ would be a shorter path than \mathbf{r} , which is impossible. Hence we have $f_h = \{u_h, u_{h+1}\}$ for $0 \leq h \leq r$. Then (u_1, u_2, \dots, u_r) is an $(r-1)$ -path in Γ , $\{u_1\} = e_0 \cap f_1 \subseteq \{v_0, v_1\}$ and $\{u_r\} = f_{r-1} \cap e_{s-1} \subseteq \{v_{s-1}, v_s\}$. It follows that $d_\Gamma(v_0, v_s) \leq d_\Gamma(u_1, u_r) + 2 \leq r + 1 < s$, contradicting the fact that \mathbf{a} is an s -geodesic. Therefore, $\mathcal{L}_s(\mathbf{a})$ is an $(s-1)$ -geodesic of $L(\Gamma)$.

(3) Let $2 \leq s \leq \text{diam}(L(\Gamma)) + 1$ and \mathcal{G}_{s-1} be the set of all $(s-1)$ -geodesics of $L(\Gamma)$. If $s = 2$, then by part (1), each 1-geodesic of $L(\Gamma)$ lies in the image $\text{Im}(\mathcal{L}_2)$, and hence $\mathcal{G}_1 \subseteq \text{Im}(\mathcal{L}_2)$. Now suppose inductively that $2 \leq s \leq \text{diam}(L(\Gamma))$ and $\mathcal{G}_{s-1} \subseteq \text{Im}(\mathcal{L}_s)$. Let $\mathbf{e} = (e_0, e_1, e_2, \dots, e_s)$ be an s -geodesic of $L(\Gamma)$. Then $\mathbf{e}' = (e_0, e_1, e_2, \dots, e_{s-1})$ is an $(s-1)$ -geodesic of $L(\Gamma)$. Thus there exists an s -arc \mathbf{a} of Γ such that $\mathcal{L}_s(\mathbf{a}) = \mathbf{e}'$, say $\mathbf{a} = (v_0, v_1, \dots, v_s)$. Since e_s is adjacent to $e_{s-1} = \{v_{s-1}, v_s\}$ but not to $e_{s-2} = \{v_{s-2}, v_{s-1}\}$ in $L(\Gamma)$, it follows that $e_s = \{v_s, x\}$ where $x \notin \{v_{s-2}, v_{s-1}\}$. Hence $\mathbf{b} = (v_0, v_1, \dots, v_s, x)$ is an $(s+1)$ -arc of Γ . Further, $\mathcal{L}_{s+1}(\mathbf{b}) = \mathbf{e}$. Thus $\text{Im}(\mathcal{L}_{s+1})$ contains all s -geodesics of $L(\Gamma)$, that is, $\mathcal{G}_s \subseteq \text{Im}(\mathcal{L}_{s+1})$. Hence the first part of (3) is proved by induction.

Now we prove the second part. Suppose first that for every s -arc \mathbf{a} of Γ , $\mathcal{L}_s(\mathbf{a})$ is an $(s-1)$ -geodesic of $L(\Gamma)$. Let $g := \text{girth}(\Gamma)$. If $s = 2$, as $g \geq 3$, then $g \geq 2s - 2$. Now let $s \geq 3$. Assume that $g \leq 2s - 3$. Then Γ has a g -cycle $\mathbf{b} = (u_0, u_1, u_2, \dots, u_{g-1}, u_g)$ with $u_g = u_0$. It follows that $\mathcal{L}_g(\mathbf{b})$ forms a g -cycle of $L(\Gamma)$. Thus the sequence $\mathbf{b}' = (u_0, u_1, \dots, u_s)$ (where we take subscripts modulo g if necessary) is an s -arc of Γ and $\mathcal{L}_s(\mathbf{b}') = (e_0, e_1, \dots, e_{s-1})$ involves only the vertices of $\mathcal{L}_s(\mathbf{b})$. This implies that $d_{L(\Gamma)}(e_0, e_{s-1}) \leq \frac{g}{2} \leq \frac{2s-3}{2} < s-1$, that is, $\mathcal{L}_s(\mathbf{b}')$ is not an $(s-1)$ -geodesic, which is a contradiction. Thus, $g \geq 2s - 2$.

Conversely, suppose that $g \geq 2s - 2$. Let $\mathbf{a} := (v_0, v_1, v_2, \dots, v_s)$ be an s -arc of Γ . Then $\mathcal{L}_s(\mathbf{a}) = (e_0, e_1, e_2, \dots, e_{s-1})$ is an $(s-1)$ -arc of $L(\Gamma)$ by part (1). Let $\mathbf{a}' := (v_0, v_1, v_2, \dots, v_{s-1})$. Since $g \geq 2s - 2$, it follows that \mathbf{a}' is an $(s-1)$ -geodesic, and hence by (2), $\mathcal{L}_{s-1}(\mathbf{a}') = (e_0, e_1, e_2, \dots, e_{s-2})$ is an $(s-2)$ -geodesic of $L(\Gamma)$. Thus $z = d_{L(\Gamma)}(e_0, e_{s-1})$ satisfies $s-3 \leq z \leq s-1$. There is a z -geodesic from e_0 to e_{s-1} , say $\mathbf{f} = (e_0, f_1, f_2, \dots, f_{z-1}, e_{s-1})$. Further, by the first part of (3), there is a $(z+1)$ -arc $\mathbf{b} = (u_0, u_1, \dots, u_z, u_{z+1})$ of Γ such that $\mathcal{L}_{z+1}(\mathbf{b}) = \mathbf{f}$ and we have $e_0 = \{u_0, u_1\} = \{v_0, v_1\}$ and $e_{s-1} = \{u_z, u_{z+1}\} = \{v_{s-1}, v_s\}$. There are 4 cases, in columns 2 and 3 of Table 1: in each case there is a given nondegenerate closed walk \mathbf{x} of length $l(\mathbf{x})$ as in Table 1. Thus $l(\mathbf{x}) \geq g \geq 2s - 2$ and in each case $l(\mathbf{x}) \leq s + z - 1$. It follows that $z \geq s - 1$, and hence $z = s - 1$. Thus $\mathcal{L}_s(\mathbf{a}) = (e_0, e_1, e_2, \dots, e_{s-1})$ is an $(s-1)$ -geodesic of $L(\Gamma)$.

(4) This property follows from the definition of \mathcal{L}_s . \square

Table 1: Four cases of \mathbf{x}

Case	(u_0, u_1)	(u_z, u_{z+1})	\mathbf{x}	$l(\mathbf{x})$
1	(v_0, v_1)	(v_{s-1}, v_s)	$(v_{s-1}, v_{s-2}, \dots, v_2, v_1, u_2, \dots, u_{z-1}, v_{s-1})$	$s + z - 3$
2	(v_0, v_1)	(v_s, v_{s-1})	$(v_s, v_{s-1}, \dots, v_2, v_1, u_2, \dots, u_{z-1}, v_s)$	$s + z - 2$
3	(v_1, v_0)	(v_{s-1}, v_s)	$(v_{s-1}, v_{s-2}, \dots, v_2, v_1, u_1, u_2, \dots, u_{z-1}, v_{s-1})$	$s + z - 2$
4	(v_1, v_0)	(v_s, v_{s-1})	$(v_s, v_{s-1}, \dots, v_2, v_1, u_1, u_2, \dots, u_{z-1}, v_s)$	$s + z - 1$

Remark 2.5. (i) The map \mathcal{L}_s is usually not surjective on the set of $(s - 1)$ -arcs of $L(\Gamma)$. In the proof of Theorem 2.4 (1), we constructed an $(s - 1)$ -arc of $L(\Gamma)$ not in $\text{Im}(\mathcal{L}_s)$ for any Γ with at least one vertex of valency at least 3.

(ii) Theorem 2.4 (1) and (3) imply that, for each $(s - 1)$ -geodesic \mathbf{e} of $L(\Gamma)$, there is a unique s -arc \mathbf{a} of Γ such that $\mathcal{L}_s(\mathbf{a}) = \mathbf{e}$. The s -arc \mathbf{a} is not always an s -geodesic. For example, if Γ has girth 3 and (v_0, v_1, v_2, v_0) is a 3-cycle, then $\mathbf{a} = (v_0, v_1, v_2)$ is not a 2-geodesic but $\mathcal{L}_2(\mathbf{a})$ is the 1-geodesic (e_0, e_1) where $e_0 = \{v_0, v_1\}$ and $e_1 = \{v_1, v_2\}$.

2.2 Proofs of Theorem 1.1 and Corollary 1.2

Proof of Theorem 1.1. Let Γ be a connected, regular, non-complete graph of girth g and valency at least 3. Then in particular $|V(\Gamma)| \geq 5$, and by Lemma 2.1, $\text{Aut}(\Gamma) \cong \text{Aut}(L(\Gamma))$. Let $G \leq \text{Aut}(\Gamma)$ and let $2 \leq s \leq \text{diam}(L(\Gamma)) + 1$.

Suppose first that G is transitive on the set of s -arcs of Γ . Then by [3, Proposition 17.2], $s \leq g/2 + 1$. Since $s - 1 \leq \text{diam}(L(\Gamma))$, it follows that $L(\Gamma)$ has $(s - 1)$ -geodesics and by Theorem 2.4 (3), $\text{Im}(\mathcal{L}_s)$ is the set of $(s - 1)$ -geodesics of $L(\Gamma)$. On the other hand, by Theorem 2.4 (4), G acts transitively on $\text{Im}(\mathcal{L}_s)$, and hence G is transitive on the set of $(s - 1)$ -geodesics of $L(\Gamma)$.

Conversely, suppose that $s \leq g/2 + 1$ and G is transitive on the $(s - 1)$ -geodesics of $L(\Gamma)$. Then by the last assertion of Theorem 2.4 (3), $\text{Im}(\mathcal{L}_s)$ is the set of $(s - 1)$ -geodesics, and since \mathcal{L}_s is injective, it follows from Theorem 2.4 (1) and (4) that G is transitive on the set of s -arcs of Γ . □

Proof of Corollary 1.2. Let Γ, g, s be as in Theorem 1.1. Assume that $\text{Aut}(\Gamma)$ is transitive on the $(s - 1)$ -geodesics of $L(\Gamma)$. If $s > 7$, then by [21], $\text{Aut}(\Gamma)$ is not transitive on the s -arcs of Γ and so by Theorem 1.1, $s > \frac{g}{2} + 1$. □

3 2-geodesic transitive graphs that are locally cyclic or locally $2K_2$

In this section, we prove Theorem 1.3. The proof uses the notion of a clique graph. A *maximum clique* of a graph Γ is a clique (complete subgraph) which is not contained in a larger clique. The *clique graph* $C(\Gamma)$ of Γ is the graph with vertices the maximum cliques of Γ , and two maximum cliques are adjacent if and only if they have at least one common vertex in Γ .

Proof of Theorem 1.3. Let Γ be a connected non-complete graph of girth 3 and valency 4, and let $A = \text{Aut}(\Gamma)$ and $v \in V(\Gamma)$. Suppose first that Γ is 2-geodesic transitive. Then Γ is arc transitive, and so A_v is transitive on $\Gamma(v)$. Since Γ is non-complete of girth 3, $[\Gamma(v)]$ is neither complete nor edgeless, and so, as discussed before the statement of Theorem 1.3, $[\Gamma(v)] = C_4$ or $2K_2$. If $[\Gamma(v)] \cong C_4$, then it is easy to see that $\Gamma \cong \mathcal{O}$ (or see [4, p.5] or [5]). So we may assume that $[\Gamma(v)] \cong 2K_2$. It follows from [8, Theorem 1.4] that Γ is isomorphic to the clique graph $C(\Sigma)$ of a connected graph Σ such that, for each $u \in V(\Sigma)$, the induced subgraph $[\Sigma(u)] \cong 3K_1$, that is to say, Σ is a cubic graph of girth at least 4 and $C(\Sigma)$ is in this case the line graph $L(\Sigma)$. Moreover, [8, Theorem 1.4] gives that $\Sigma \cong C(\Gamma)$. A cubic graph with girth at least 4 has $|V(\Sigma)| \geq 5$, so by Lemma 2.1, $A \cong \text{Aut}(\Sigma)$. Now we apply Theorem 1.1 to the graph Σ of girth $g \geq 4$. Since $\Gamma = L(\Sigma)$ is 2-geodesic transitive and $3 \leq g/2 + 1$, it follows from Theorem 1.1 that Σ is 3-arc transitive. Therefore, Γ is the line graph of a 3-arc transitive cubic graph.

Conversely, if $\Gamma \cong \mathcal{O}$, then it is 2-geodesic transitive, and hence is geodesic transitive as $\text{diam}(\mathcal{O}) = 2$. If $\Gamma = L(\Sigma)$ where Σ is a 3-arc transitive cubic graph, then by Theorem 1.1 applied to Σ with $s = 3$, $L(\Sigma)$ is 2-geodesic transitive. This proves the first assertion of Theorem 1.3.

To prove the second assertion, suppose first that Γ is geodesic transitive. Then Γ is distance transitive, and so by Theorems 7.5.2 and 7.5.3 (i) of [4], Γ is one of the following graphs: $\mathcal{O} = L(K_4)$, $H(2, 3) = L(K_{3,3})$, or the line graph of the Petersen graph, the Heawood graph or Tutte's 8-cage. We complete the proof by showing that all these graphs are geodesic transitive. As noted above, \mathcal{O} is geodesic transitive; by [7, Proposition 3.2], $H(2, 3)$ is geodesic transitive. It remains to consider the last three graphs.

Let Σ be the Petersen graph and $\Gamma = L(\Sigma)$. Then Σ is 3-arc transitive, and it follows from Theorem 1.1 that Γ is 2-geodesic transitive. By [4, Theorem 7.5.3 (i)], $\text{diam}(\Gamma) = 3$ and $|\Gamma(w) \cap \Gamma_3(u)| = 1$ for each 2-geodesic (u, v, w) of Γ . Thus Γ is 3-geodesic transitive, and hence is geodesic transitive.

Let Σ_1 be the Heawood graph and Σ_2 be Tutte's 8-cage. Then Σ_1 is 4-arc transitive and Σ_2 is 5-arc transitive, and hence by Theorem 1.1, $L(\Sigma_1)$ is 3-geodesic transitive and $L(\Sigma_2)$ is 4-geodesic transitive. By [4, Theorem 7.5.3 (i)], $\text{diam}(L(\Sigma_1)) = 3$ and $\text{diam}(L(\Sigma_2)) = 4$, and hence both $L(\Sigma_1)$ and $L(\Sigma_2)$ are geodesic transitive. \square

Finally, we prove Corollary 1.4.

Proof of Corollary 1.4. Let Γ be a connected non-complete locally cyclic graph. If Γ is 2-geodesic transitive, then it is regular of valency n say. As discussed in the introduction, $n = 4$ or 5 . If $n = 4$, then we proved in Theorem 1.3, that Γ is isomorphic to the octahedron and that the octahedron is indeed 2-geodesic transitive. If $n = 5$, then by [7, Theorem 1.2], Γ is isomorphic to the icosahedron, and this graph is 2-geodesic transitive. \square

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